

Answers final exam

Quantum Physics I of 28 Nov 2013

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Problem 1

a) The eigen values can be calculated using

$$\hat{H}|q_g\rangle = E_g|q_g\rangle \text{ and } \hat{H}|q_e\rangle = E_e|q_e\rangle$$

$$E_g: \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}}(E_0+T) \\ \frac{1}{\sqrt{2}}(E_0+T) \end{pmatrix} = (E_0+T) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow$$

$$E_g = E_0 + T = E_0 - |T|$$

$$E_e \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} E_0 - T \\ E_0 - T \end{pmatrix} = (E_0 - T) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow$$

$$E_e = E_0 - T = E_0 + |T|$$

b) $\langle \varphi_e | \hat{H} | \varphi_e \rangle = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = E_0$

The expectation value for total energy when the particle is in state $|\varphi_g\rangle$

$$\langle \varphi_g | \hat{H} | \varphi_g \rangle = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = E_0$$

The same, for the state $|\varphi_e\rangle$

$$\langle \varphi_e | \hat{H} | \varphi_e \rangle = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = T$$

The energy scale associated with the tunnel coupling between the states $|\varphi_e\rangle$ and $|\varphi_g\rangle$.

$$\langle \varphi_e | \hat{H} | \varphi_e \rangle = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = T \Rightarrow \text{Same meaning as } \langle \varphi_e | \hat{H} | \varphi_g \rangle$$

c) $\langle \varphi_g | \hat{H} | \varphi_g \rangle = \langle \varphi_g | E_g | \varphi_g \rangle = E_g$ (using a))

$$\langle \varphi_e | \hat{H} | \varphi_e \rangle = \langle \varphi_e | E_e | \varphi_e \rangle = E_e \text{ (using a))}$$

These are the expectation values and also eigenvalues for total energy for the system in the state $|\varphi_g\rangle$ and $|\varphi_e\rangle$.

$$\langle \varphi_g | \hat{H} | \varphi_e \rangle = \langle \varphi_e | \hat{H} | \varphi_g \rangle = 0$$

since the eigen states are orthogonal.

This gives that there is no further meaning that the states are orthogonal, no coupling = zero coupling energy between $|\varphi_g\rangle$ and $|\varphi_e\rangle$.

d) The state $\alpha|\varphi_g\rangle + \beta|\varphi_e\rangle$ is normalized

for $|\alpha|^2 + |\beta|^2 = 1$. For $|\varphi_0\rangle$ this gives

$$|3|^2 + |e^{iy}|^2 = |3|^2 + |1|^2 = 10. \text{ The normalized}$$

$$\text{version } |\varphi_{0N}\rangle \text{ of } |\varphi_0\rangle \text{ is thus } |\varphi_{0N}\rangle = \frac{1}{\sqrt{10}}(3|\varphi_g\rangle + e^{iy}|\varphi_e\rangle).$$

Now calculate $\langle \hat{A} \rangle = \langle \varphi_{0N} | \hat{A} | \varphi_{0N} \rangle$

$$= \frac{1}{10} \begin{pmatrix} 3 & e^{-iy} \\ \frac{3}{\sqrt{2}} + \frac{e^{-iy}}{\sqrt{2}} & \frac{3}{\sqrt{2}} - \frac{e^{-iy}}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -\alpha & 0 \\ 0 & \alpha \end{pmatrix} \begin{pmatrix} \frac{3}{\sqrt{2}} + \frac{e^{iy}}{\sqrt{2}} \\ \frac{3}{\sqrt{2}} - \frac{e^{iy}}{\sqrt{2}} \end{pmatrix} =$$

$$= \frac{\alpha}{10} \begin{pmatrix} \frac{3}{\sqrt{2}} + \frac{e^{-iy}}{\sqrt{2}} & \frac{3}{\sqrt{2}} - \frac{e^{-iy}}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -\frac{3}{\sqrt{2}} - \frac{e^{iy}}{\sqrt{2}} \\ \frac{3}{\sqrt{2}} - \frac{e^{iy}}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{3}{\sqrt{2}} + \frac{e^{iy}}{\sqrt{2}} \\ \frac{3}{\sqrt{2}} - \frac{e^{iy}}{\sqrt{2}} \end{pmatrix}$$

$$= \frac{\alpha}{10} \begin{pmatrix} -\frac{9}{2} - \frac{1}{2} + \frac{9}{2} + \frac{1}{2} + \frac{1}{2}(-3e^{+iy} - 3e^{-iy} - 3e^{+iy} - 3e^{-iy}) \end{pmatrix}$$

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$$= \frac{-6a}{20} (e^{+iy} + e^{-iy})$$

$$= -\frac{12}{20} a \cos y = -\frac{3}{5} \cos(y) \cdot a$$

$$e) \quad |\psi(A)\rangle = e^{-\frac{i}{\hbar} H t} |\psi(t_0)\rangle = e^{-\frac{i}{\hbar} H t} |\psi_0\rangle$$

$$= \frac{1}{\sqrt{2}} (e^{-\frac{i}{\hbar} E_g t} |q_g\rangle + e^{-\frac{i}{\hbar} E_e t} |q_e\rangle)$$

$$e1) \quad \langle H | \psi \rangle = \langle \psi(A) | H | \psi(A) \rangle = \frac{1}{2} \left(e^{+\frac{i}{\hbar} E_g t} \langle q_g | + e^{+\frac{i}{\hbar} E_e t} \langle q_e | \right) \left(\frac{1}{\sqrt{2}} |q_g\rangle + e^{-\frac{i}{\hbar} E_g t} \frac{1}{\sqrt{2}} |q_e\rangle \right)$$

$$= \frac{1}{2} (\langle q_g | H | q_g \rangle + \langle q_e | H | q_e \rangle) = \frac{1}{2} (E_g + E_e) = E_0$$

e2) Matrix for potential energy is $\hat{V} \leftrightarrow \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \Rightarrow$

$$\langle \hat{V} | \psi \rangle = \langle \psi(A) | \hat{V} | \psi(A) \rangle = \frac{1}{2} \left(e^{+\frac{i}{\hbar} E_g t} \langle q_g | + e^{+\frac{i}{\hbar} E_e t} \langle q_e | \right) \left(\frac{1}{\sqrt{2}} |q_g\rangle + e^{-\frac{i}{\hbar} E_g t} \frac{1}{\sqrt{2}} |q_e\rangle \right)$$

As intermediate step calculate $\langle q_g | \hat{V} | q_g \rangle, \langle q_e | \hat{V} | q_e \rangle, \langle q_g | \hat{V} | q_e \rangle, \langle q_e | \hat{V} | q_g \rangle$

$$\langle q_g | \hat{V} | q_g \rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = E_0$$

$$\langle q_e | \hat{V} | q_e \rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = E_0$$

$$\langle q_g | \hat{V} | q_e \rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = 0$$

$$\langle q_e | \hat{V} | q_g \rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0$$

$$\langle \hat{V} | \psi \rangle = \frac{1}{2} (\langle q_g | \hat{V} | q_g \rangle + \langle q_e | \hat{V} | q_e \rangle) = \frac{1}{2} (E_0 + E_0) = E_0$$

Problem 2

$$a) \quad \hat{X} \delta(x-x_n) = x_n \delta(x-x_n) \quad \text{OR}$$

$$\hat{X} |x_n\rangle = x_n |x_n\rangle$$

\hat{X} is the position operator.

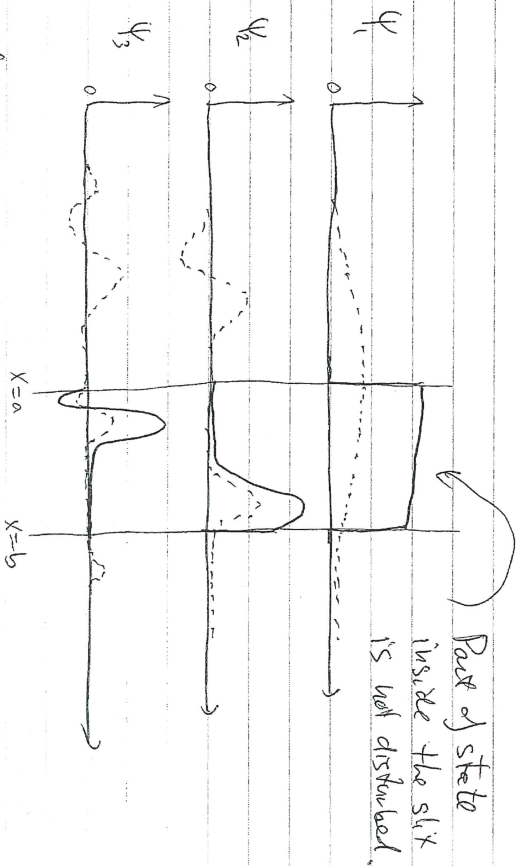
$\delta(x-x_n)$ or $|x_n\rangle$ denotes the eigen state for position eigenvalue x_n .

b) The position eigenstate is a Dirac delta function located at the position of the eigenvalue, which then is x_n .

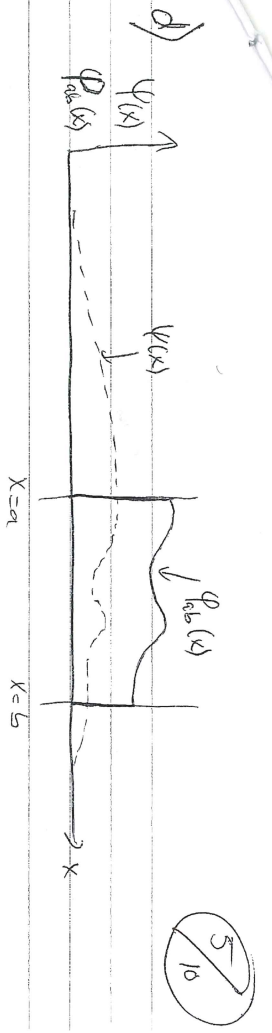
Such a state can never be realized in practice, because it would have uncertainty $\Delta x \rightarrow 0$. This would require an uncertainty in momentum $\Delta p \rightarrow \infty$, which costs an infinite amount of energy. So, it is impossible.

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c)



----- before measurement
----- after measurement (higher amplitude to maintain normalization)



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State before measurement is $\psi(x)$

State after measurement is $\phi_{ab}(x) = \begin{cases} 0 & \text{for } x < a, x > b \\ C \cdot \psi(x) & \text{for } a \leq x \leq b \end{cases}$

where C is a constant that accounts for the normalization.

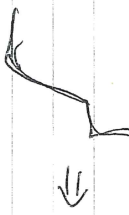
$$\int_a^b |\phi_{ab}(x)|^2 dx = \int_a^b |C \psi(x)|^2 dx = 1 \Rightarrow \int_a^b |\psi(x)|^2 dx = \frac{1}{C^2}$$

$$P_{ab} = |\langle \phi_{ab} | \psi \rangle|^2 = \left| \int_a^b \phi_{ab}^*(x) \psi(x) dx \right|^2$$

$$= \left| \int_a^b C |\psi(x)|^2 dx \right|^2 = |C|^2 \left| \int_a^b |\psi(x)|^2 dx \right|^2 = |C|^2 P_{ab}^2$$

But also

$$P_{ab} = \int_a^b |\psi(x)|^2 dx = \frac{1}{C^2}$$



$$P_{ab} = |C|^2 P_{ab}^2 = \frac{1}{P_{ab}} \cdot P_{ab}^2 = P_{ab} \Rightarrow P_{ab} = P_{ab}$$

Q.E.D.

Problem 3

(6/10)

a) $S_2 \Leftrightarrow \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $S_4 \Leftrightarrow \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$S_x \Leftrightarrow \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$$H = -\gamma B_2 S_z \Leftrightarrow -\gamma B_2 \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} -\gamma B_2 \frac{1}{2} & 0 \\ 0 & +\gamma B_2 \frac{1}{2} \end{pmatrix}$$

b) $S_x \Leftrightarrow \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ To find the eigenvalues

Solve $\begin{vmatrix} (0-\lambda) & \frac{1}{2} \\ \frac{1}{2} & (0-\lambda) \end{vmatrix} = 0 \Rightarrow \lambda^2 - \left(\frac{1}{2}\right)^2 = 0 \Rightarrow$

$$\lambda = +\frac{1}{2} \text{ or } \lambda = -\frac{1}{2} \Leftarrow \text{The two eigenvalues}$$

To now find the eigen vectors solve

$$\frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \left(\pm \frac{1}{2} \right) \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow \frac{1}{2} \begin{pmatrix} b \\ a \end{pmatrix} = \pm \frac{1}{2} \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow$$

$a = b$ for both eigenvalues, and $|a| = |b| = \frac{1}{\sqrt{2}}$

for normalization.

For eigenvalue $+\frac{1}{2}$, $\frac{1}{2} \begin{pmatrix} b \\ a \end{pmatrix} = +\frac{1}{2} \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow$ the eigen state

is $|+\rangle \Leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

For eigenvalue $-\frac{1}{2}$, $\frac{1}{2} \begin{pmatrix} b \\ a \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow$ the eigen state

is $|-\rangle \Leftrightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$c) \Delta S_z = \sqrt{\langle \hat{S}_z^2 \rangle - \langle S_z \rangle^2}$$

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$$\langle \hat{S}_z \rangle = \left(\frac{1}{\sqrt{2}}, +i\frac{1}{\sqrt{2}} \right) \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -i\frac{1}{\sqrt{2}} \end{pmatrix} = 0 \frac{\hbar}{2}$$

$$\hat{S}_z^2 \Leftrightarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \frac{\hbar^2}{4} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \frac{\hbar^2}{4}$$

$$\langle \hat{S}_z^2 \rangle = \left(\frac{1}{\sqrt{2}}, +i\frac{1}{\sqrt{2}} \right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -i\frac{1}{\sqrt{2}} \end{pmatrix} \frac{\hbar^2}{4} = \frac{\hbar^2}{4}$$

$$\Delta S_z = \sqrt{\frac{\hbar^2}{4} - 0} = \frac{\hbar}{2}$$

$$d) \langle \uparrow | \hat{S}_x | \uparrow \rangle = (1, 0) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \frac{\hbar}{2} = 0$$

$$\langle \downarrow | \hat{S}_x | \downarrow \rangle = (0, 1) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \frac{\hbar}{2} = 0$$

$$\langle \uparrow | \hat{S}_x | \downarrow \rangle = (1, 0) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \frac{\hbar}{2} = +\frac{\hbar}{2}$$

$$\langle \downarrow | \hat{S}_x | \uparrow \rangle = (0, 1) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \frac{\hbar}{2} = +\frac{\hbar}{2}$$

$$\langle \uparrow | \hat{S}_z | \uparrow \rangle = (1, 0) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \frac{\hbar}{2} = +\frac{\hbar}{2}$$

$$\langle \downarrow | \hat{S}_z | \downarrow \rangle = (0, 1) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \frac{\hbar}{2} = -\frac{\hbar}{2}$$

$$\langle \uparrow | \hat{S}_z | \downarrow \rangle = (1, 0) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \frac{\hbar}{2} = 0$$

$$\langle \downarrow | \hat{S}_z | \uparrow \rangle = (0, 1) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \frac{\hbar}{2} = 0$$

$$e) |\psi_0\rangle = \frac{1}{\sqrt{2}} |\uparrow\rangle - i\frac{1}{\sqrt{2}} |\downarrow\rangle \Rightarrow$$

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$$|\psi(t)\rangle = e^{-iHt} |\psi_0\rangle = \frac{1}{\sqrt{2}} e^{-i\omega t} |\uparrow\rangle - i\frac{1}{\sqrt{2}} e^{-i\omega t} |\downarrow\rangle$$

$$\text{with } \omega_{\uparrow} = \frac{-\gamma B_z}{2} \text{ and } \omega_{\downarrow} = \frac{+\gamma B_z}{2}$$

$$\langle \hat{S}_x \rangle(t) = \langle \psi(t) | \hat{S}_x | \psi(t) \rangle$$

$$= \frac{1}{2} \left(e^{+i\omega_{\uparrow}t} \langle \uparrow | + i e^{+i\omega_{\downarrow}t} \langle \downarrow | \right) \hat{S}_x \left(e^{-i\omega_{\uparrow}t} |\uparrow\rangle - i e^{-i\omega_{\downarrow}t} |\downarrow\rangle \right)$$

$$= \frac{1}{2} \left(\langle \uparrow | \hat{S}_x | \uparrow \rangle + \frac{1}{2} \langle \downarrow | \hat{S}_x | \downarrow \rangle + \frac{i}{2} e^{+i(\omega_{\uparrow}-\omega_{\downarrow})t} \langle \uparrow | \hat{S}_x | \downarrow \rangle + \frac{i}{2} e^{+i(\omega_{\downarrow}-\omega_{\uparrow})t} \langle \downarrow | \hat{S}_x | \uparrow \rangle \right)$$

$$= \frac{\hbar}{2} \left(-\frac{i}{2} e^{-i(\omega_{\downarrow}-\omega_{\uparrow})t} + \frac{i}{2} e^{+i(\omega_{\downarrow}-\omega_{\uparrow})t} \right)$$

$$= \frac{\hbar}{4} \left(-i \left(\cos(\gamma B_z t) - i \sin(\gamma B_z t) \right) + i \left(\cos(\gamma B_z t) + i \sin(\gamma B_z t) \right) \right)$$

$$= \frac{\hbar}{4} \left(-2 \sin(\gamma B_z t) \right) = -\frac{\hbar}{2} \sin(\gamma B_z t)$$

Problem 4

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a) $\hat{L}_z |l, m_l\rangle = \hbar \sqrt{l(l+1)} |l, m_l\rangle$ (length)

$\hat{L}_z |l, m_l\rangle = m_l \hbar |l, m_l\rangle$ (z-comp.)

$\hat{F}|f, m_f\rangle = \hbar \sqrt{f(f+1)} |f, m_f\rangle$ (length)

$\hat{F}_z |f, m_f\rangle = m_f \hbar |f, m_f\rangle$ (z-comp.)

b) Use the rules of addition of angular momentum:

$\vec{F} = \vec{L} + \vec{S}$ with

$f = |l-j|, |l-j|+1, \dots, |l+j|-1, |l+j|$

$m_f = -f, -(f-1), -(f-2), \dots, +(f-1), +f$

With the equations of a), this gives the maximum

$m_f = 6$, so the maximum $f = 6$, so

$|l+j| = 6$. From the remark that $|\vec{L}| = \sqrt{12} \hbar$

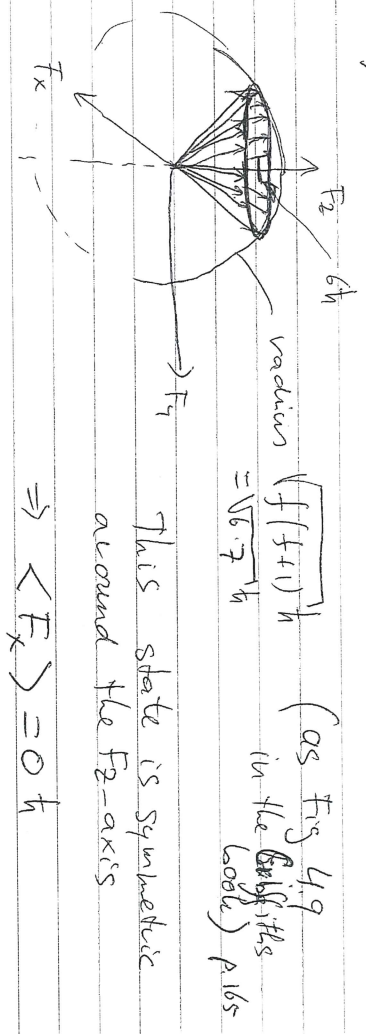
We know $l(l+1) = 12 \Rightarrow l = 3 \Rightarrow j = 3$

c) After the measurement the state of the system

is $|4\rangle = |f=6, m_f=6\rangle$, given the reasoning of question a).

c2) The state $|f=6, m_f=6\rangle$ can be drawn as

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c3) Use the uncertainty relation

$\Delta F_x \cdot \Delta F_y \geq \frac{\hbar}{2} |\langle F_z \rangle| = \frac{\hbar}{2} \cdot 6 \hbar = 3 \hbar^2 \Rightarrow$

Given the symmetry in the figure $\Delta F_x = \Delta F_y \Rightarrow$

$\Delta F_x = \Delta F_y \approx \sqrt{3} \hbar$

There is no reason for ΔF_x and ΔF_y to be much larger.

d) $j=3$ and $l=3$, so $f = 0, 1, 2, 3, 4, 5$ or 6

$|j-l| \rightarrow |j+l|$

Measurement outcomes of $|\vec{F}|$ can then yield

The values $\sqrt{f(f+1)} \Rightarrow$ The possible values are $0 \hbar, \sqrt{2} \hbar, \sqrt{6} \hbar, \sqrt{12} \hbar, \sqrt{20} \hbar, \sqrt{30} \hbar, \sqrt{42} \hbar$